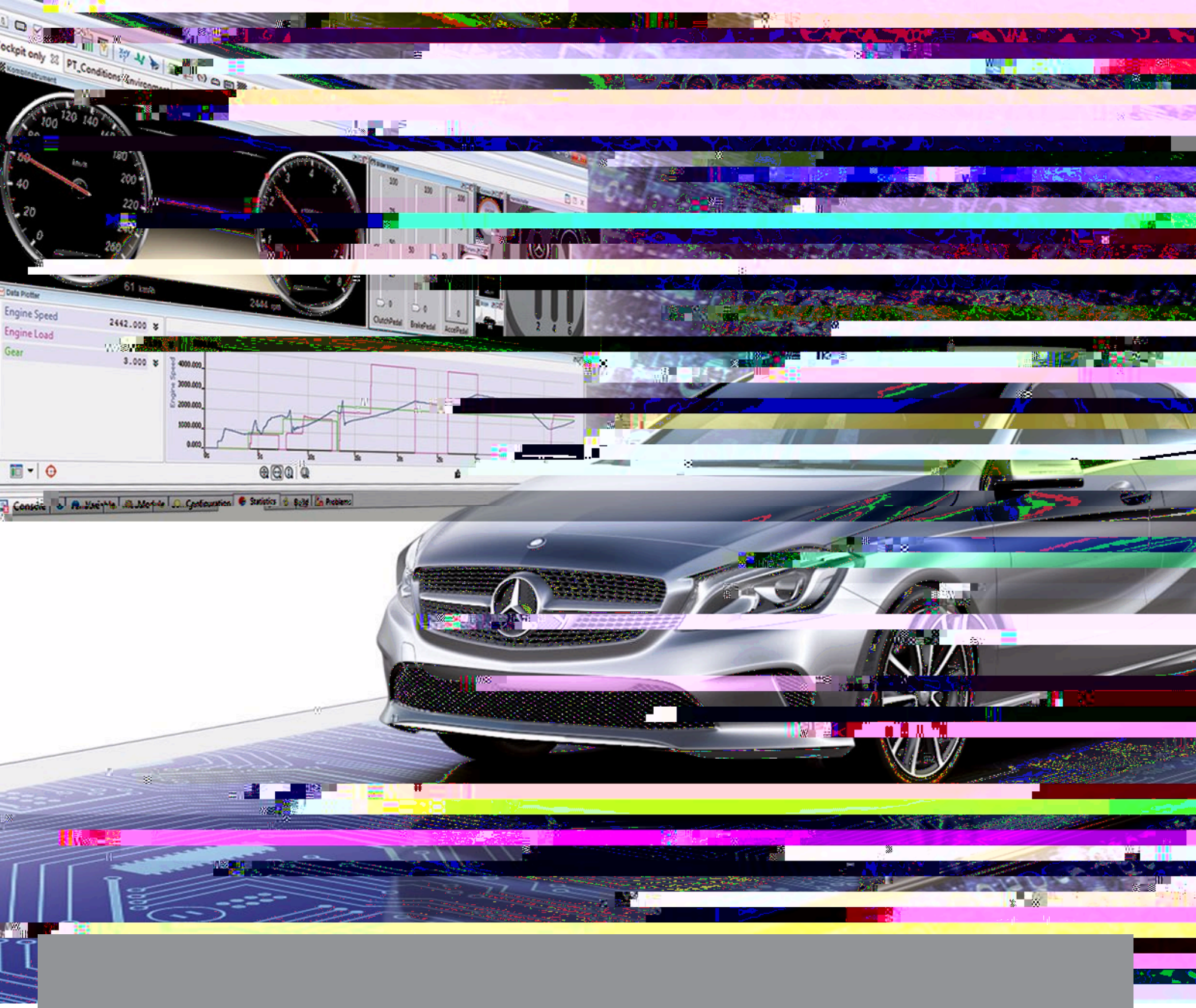

Simulation of Networked ECUs for Drivability Calibration

D -

. D

h

h

(C) h h

h u h .

h u h h

h ‘ h -

u -

h . h -

h u C ,

h h h u h

u u u
. .
-
. I u
(u 100 %,
u)

D , h u h
EC u u . B h
h ,
u u u .
h u h
u u , h
C C ,
u h R O5 (-
) h u .
B , u h -
CAN- -
u h
h R O5 ,
h u (Q
5 , 2). h , h C
C u PC h u -
h . h u
u u -
‘ (
‘ 2 – u ‘ -)
h CAN, u -

hu h h u -

FIGURE 5

FIGURE 6